

# CS221: Logic Design

## Instructors:

Dr. Ahmed Shalaby <http://bu.edu.eg/staff/ahmedshalaby14#>

Dr. Fatma Sakr

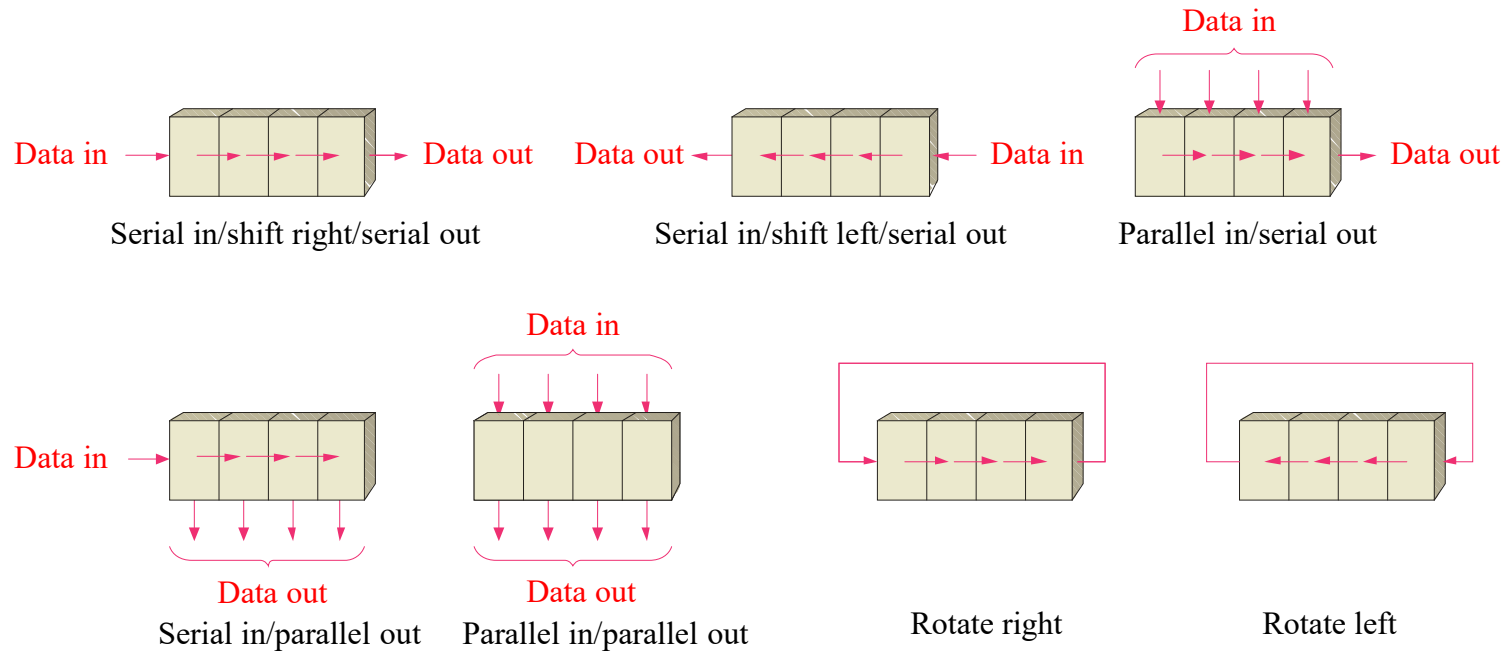
# Digital Fundamentals

## CHAPTER Shift Registers

# Shift Registers

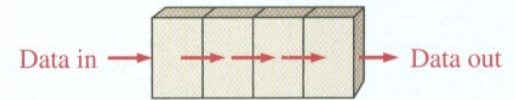
## Basic Shift Register Operations

A shift register is an arrangement of flip-flops with important applications in storage and movement of data. Some basic data movements are illustrated here.



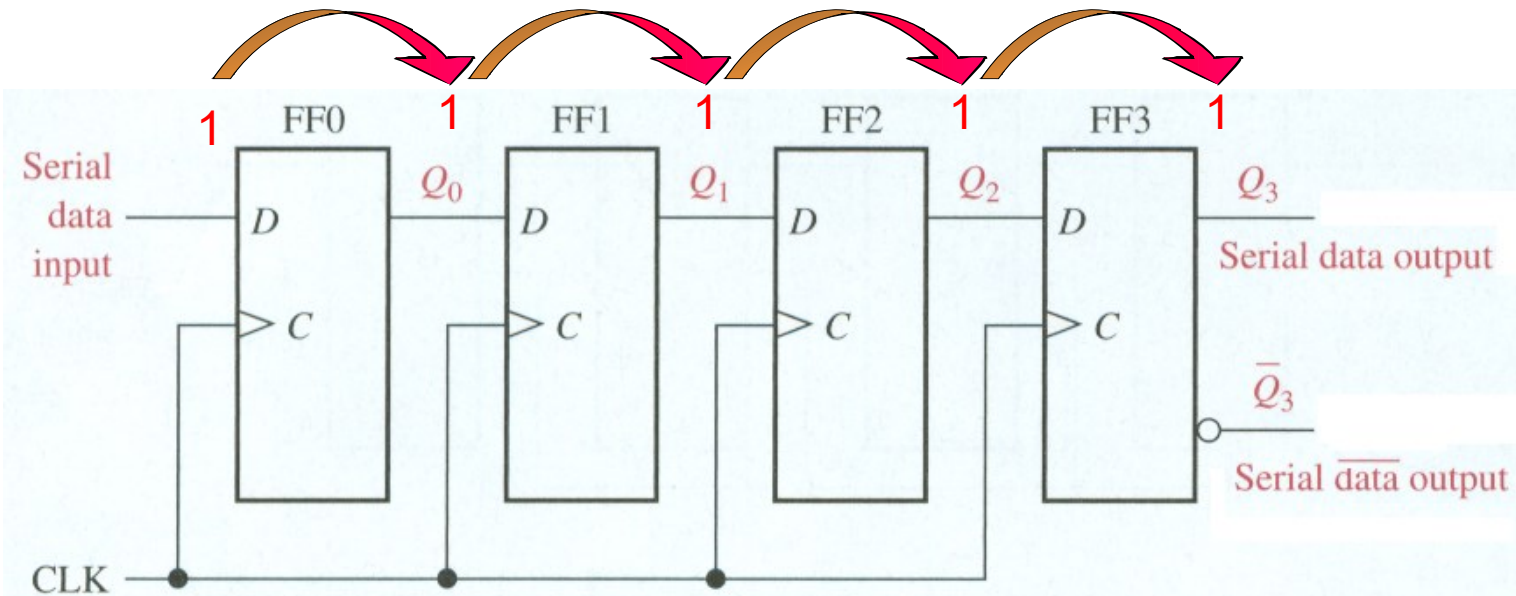
# Shift Registers

## Serial-in/Serial out Shift Register

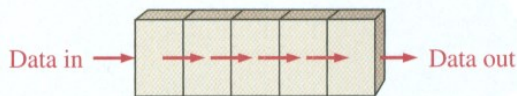


Shift registers are available in IC form or can be constructed from discrete flip-flops as is shown here with a **five-bit serial-in serial-out register**.

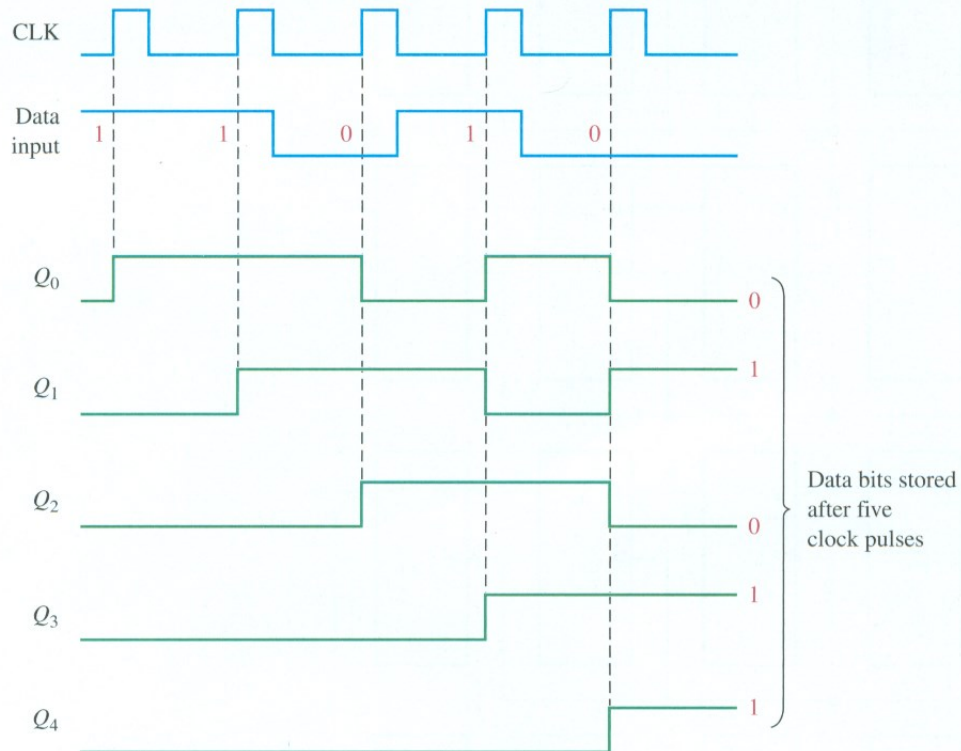
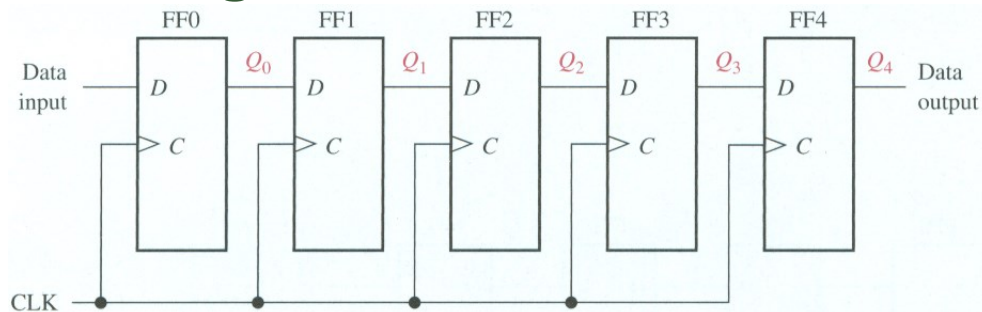
**Each clock pulse will move an input bit to the next flip-flop.** For example, a 1 is shown as it moves across.



# Serial-in/Serial out Shift Register



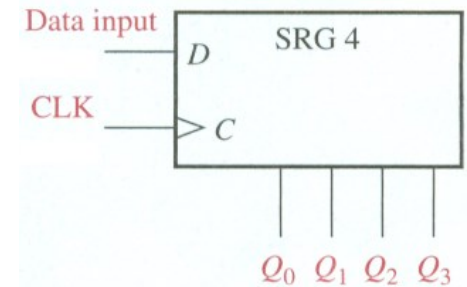
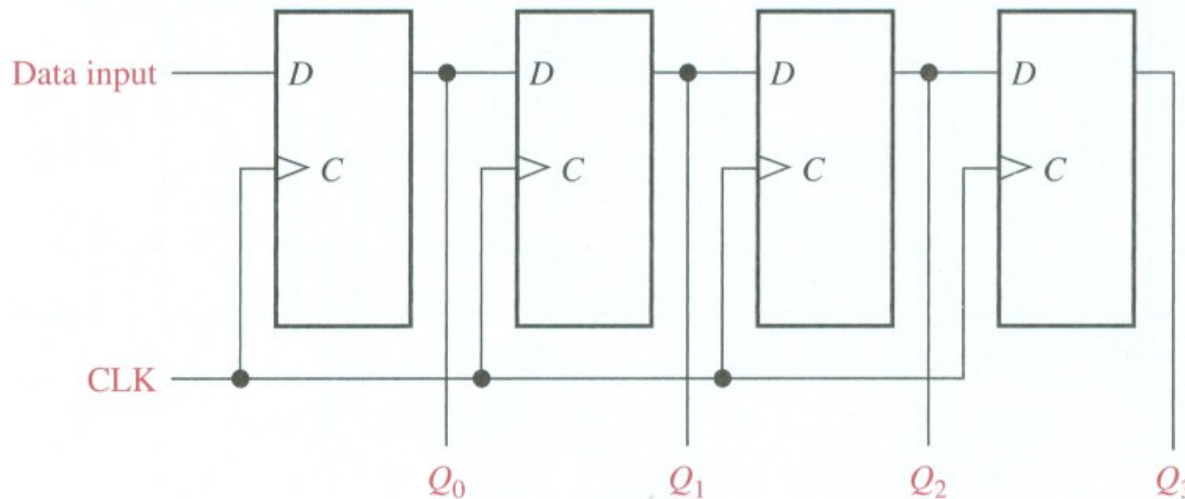
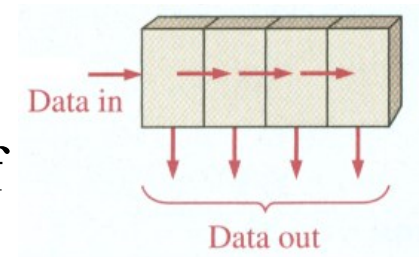
## Shift Registers



# Shift Registers

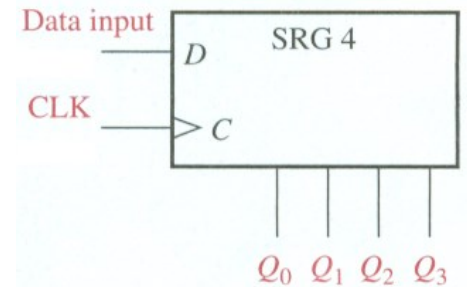
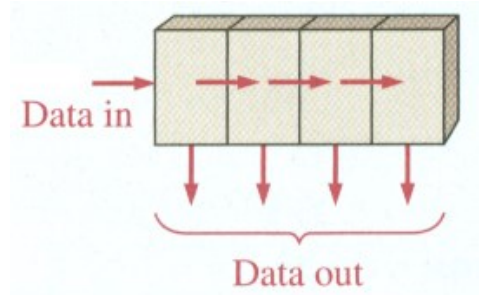
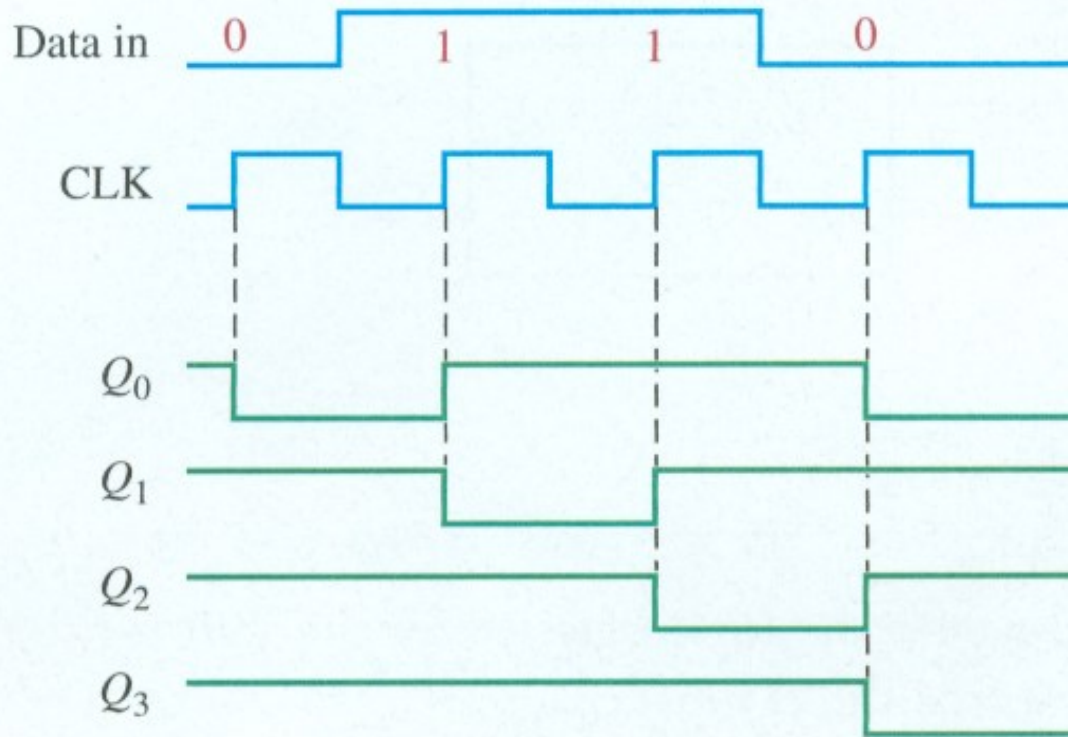
## Serial in/Parallel out Shift Register

An application of shift registers is conversion of serial data to parallel form.



# Shift Registers

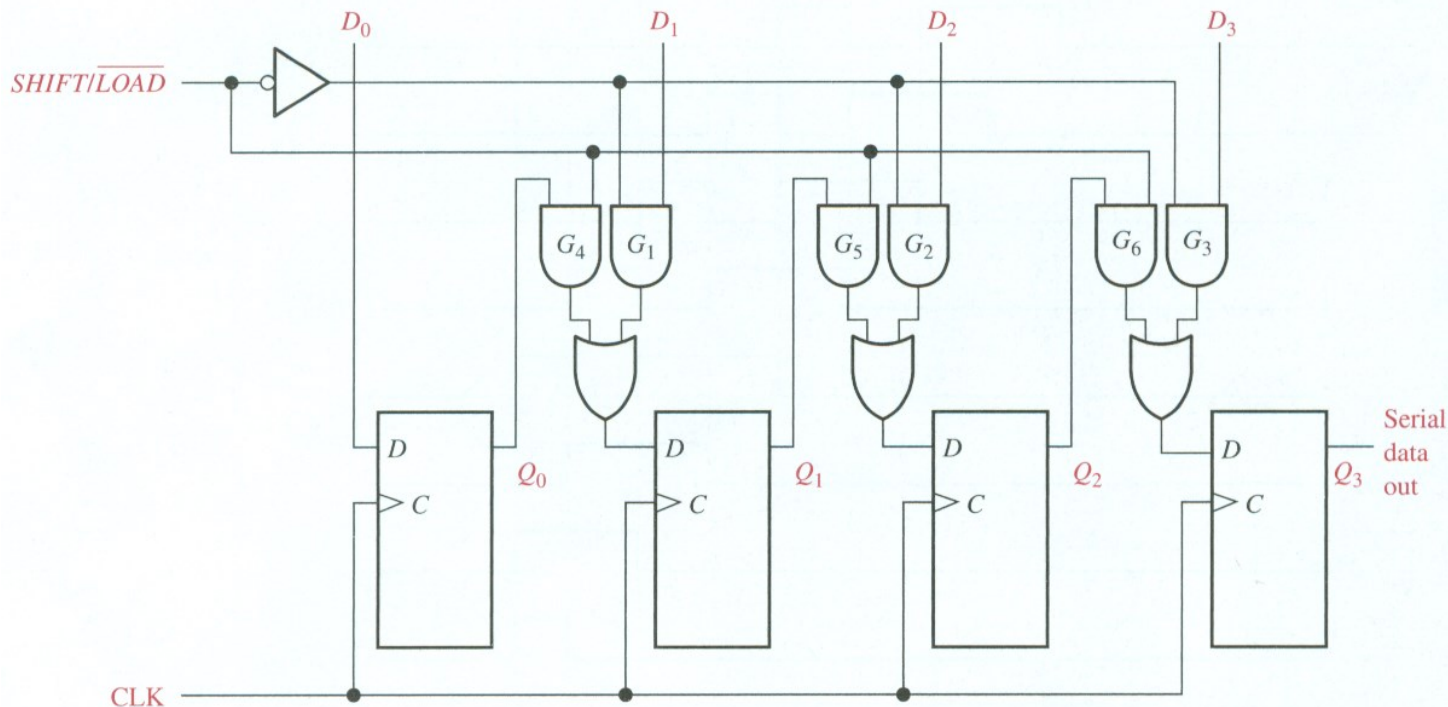
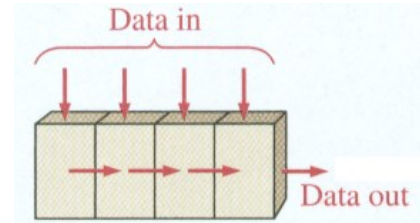
## Serial in/Parallel out Shift Register



# Shift Registers

## Parallel in/Serial out Shift Register

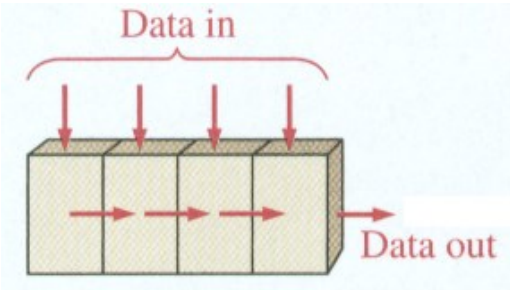
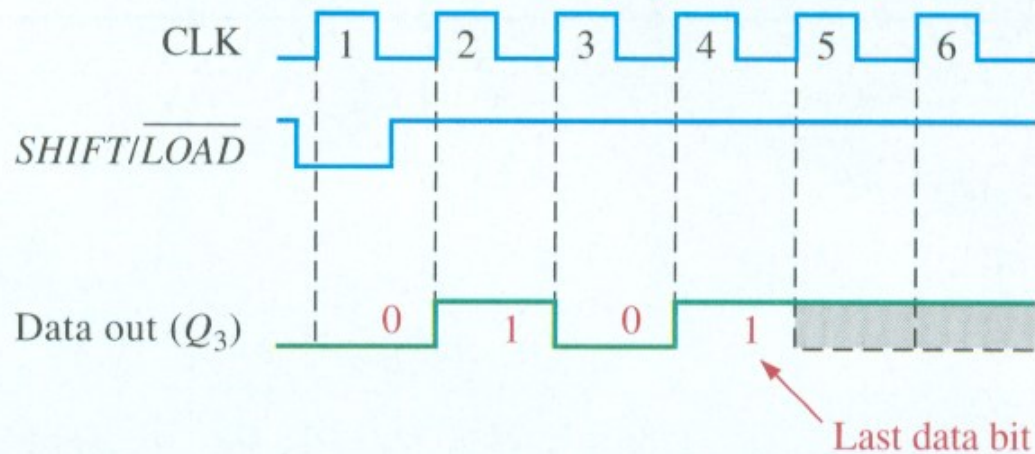
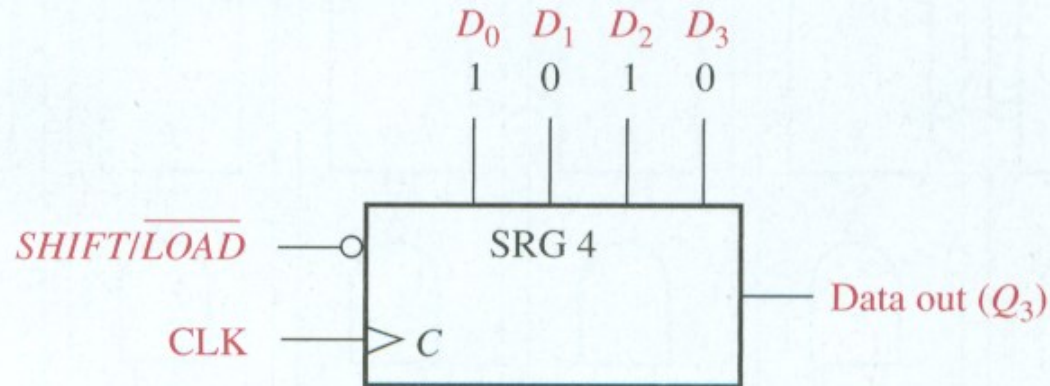
An application of shift registers is conversion of parallel data to serial form.





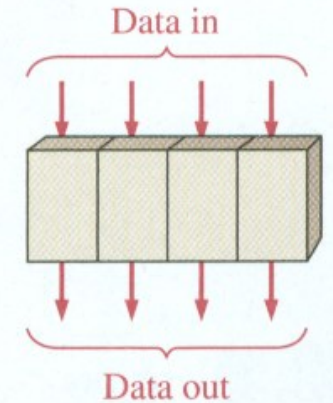
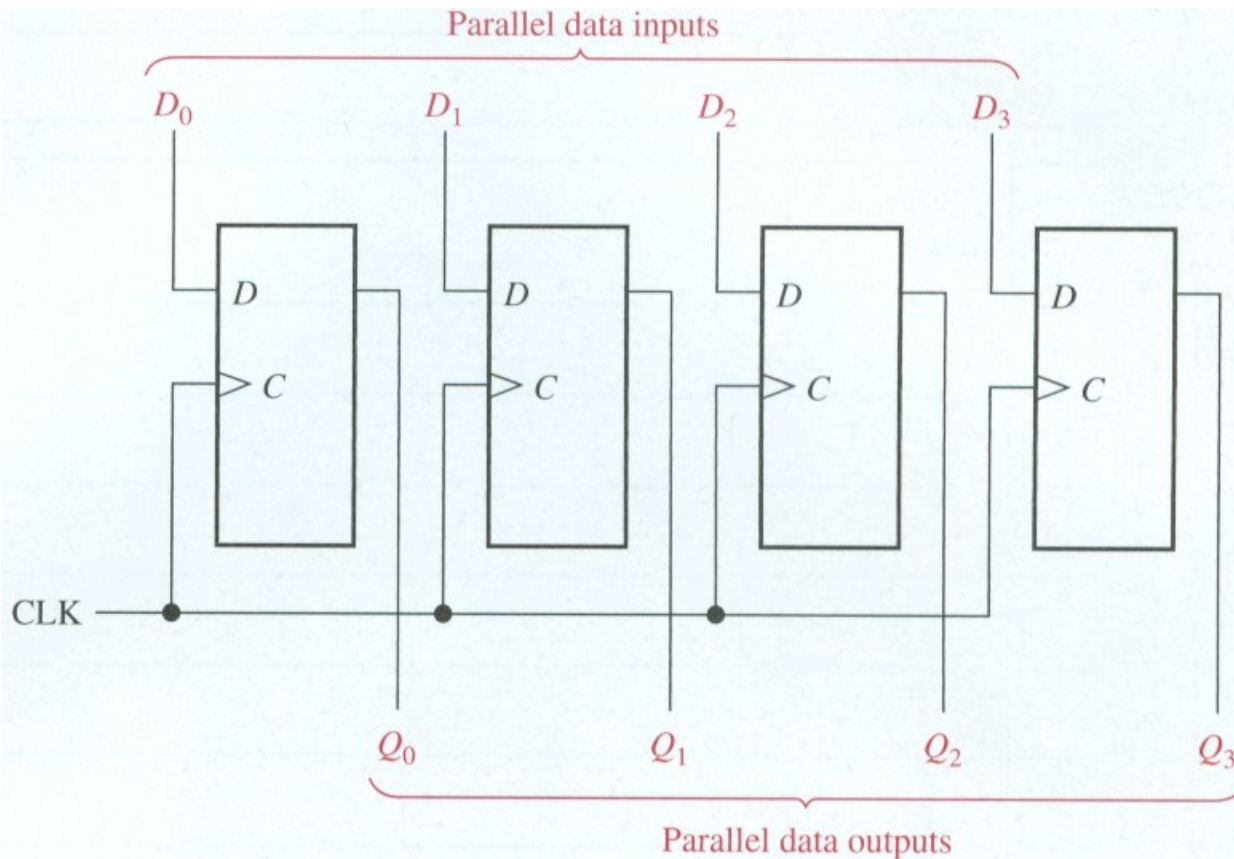
# Shift Registers

## Parallel in/Serial out Shift Register



# Shift Registers

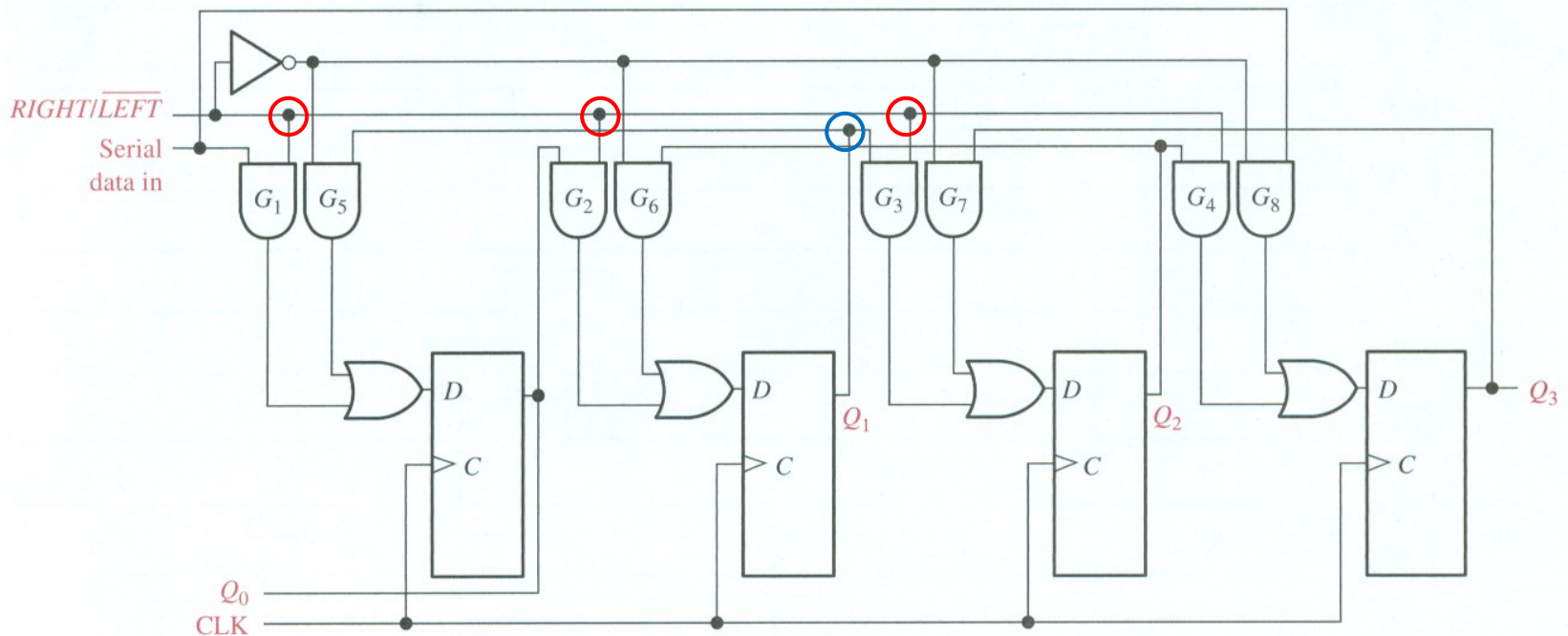
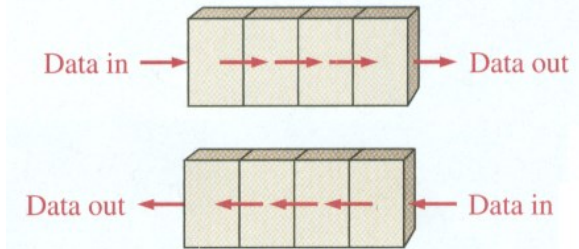
## Parallel in/Parallel out Shift Register



# Shift Registers

## Bidirectional Shift Register

Bidirectional shift registers can shift the data in either direction using a *RIGHT/LEFT* input.

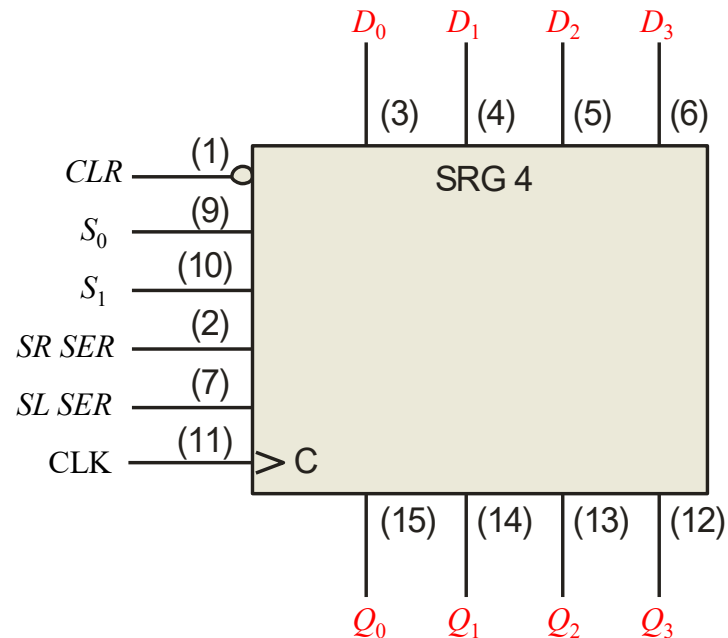


# Shift Registers

## Universal Shift Register

A universal shift register has **both serial and parallel input and output capability.**

The 74HC194 is an example of a 4-bit bidirectional universal shift register.



# Shift Registers

## Shift Register Applications

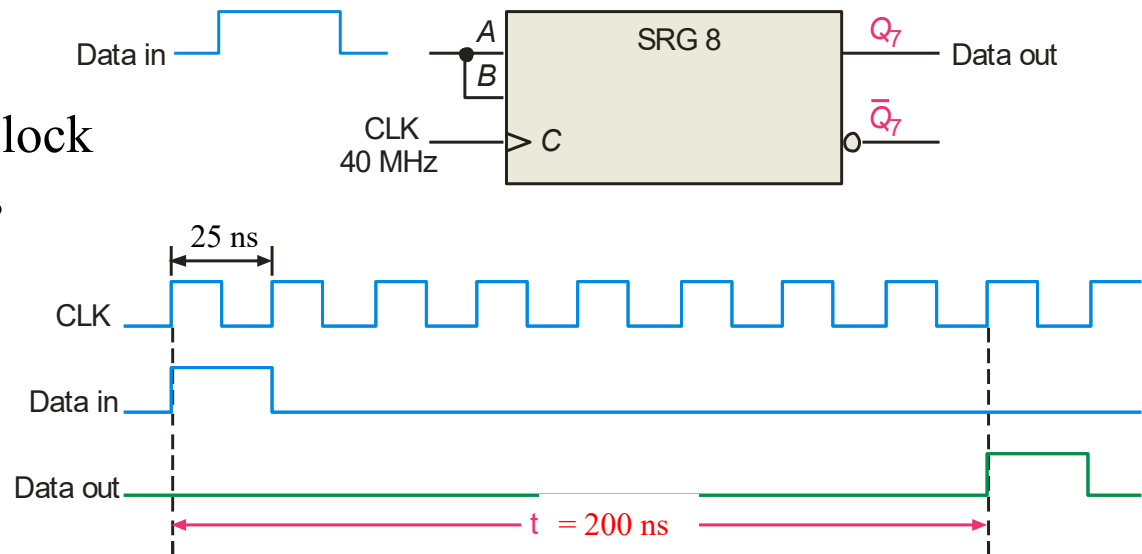
Shift registers can be used to delay a digital signal by a predetermined amount.

**Example** An 8-bit serial in/serial out shift register has a 40 MHz clock. What is the total delay through the register?

## Solution

The delay for each clock is  $1/40 \text{ MHz} = 25 \text{ ns}$

The total delay is  $8 \times 25 \text{ ns} = 200 \text{ ns}$

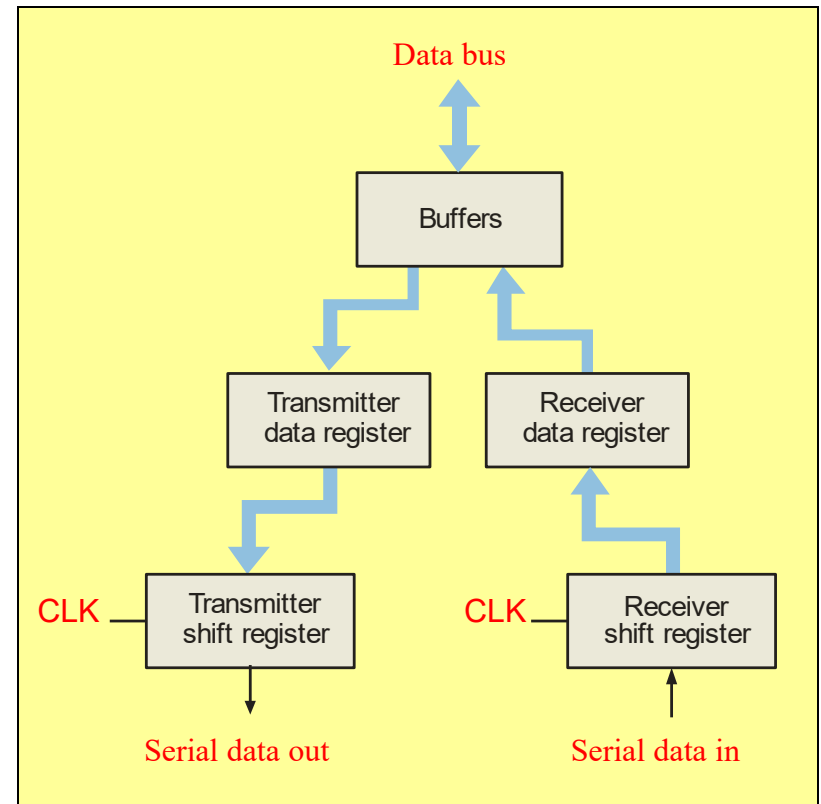


# Shift Registers

## Shift Register Applications

A UART (Universal Asynchronous Receiver Transmitter) is a serial-to-parallel converter and a parallel to serial converter.

UARTs are commonly used in small systems where one device must communicate with another. Parallel data is converted to asynchronous serial form and transmitted. The serial data format is:



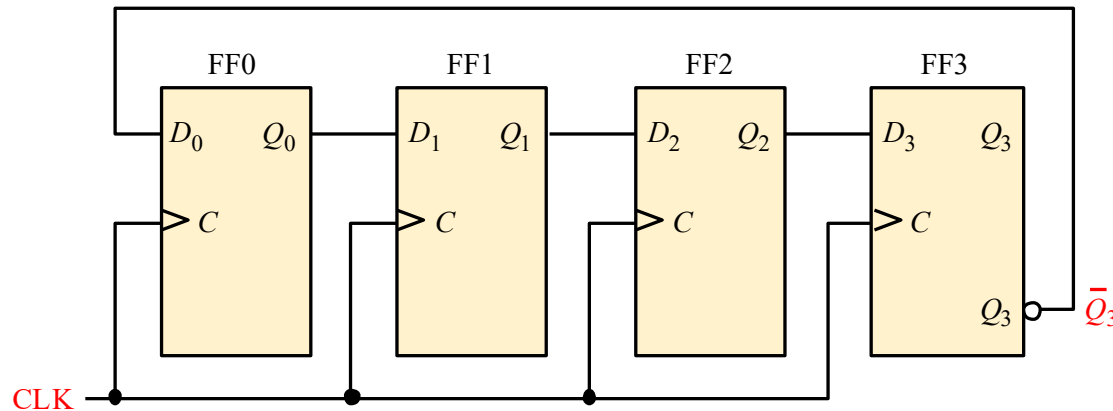
# Shift Registers

## Shift Register Counters

Inputs		Outputs		Comments
D	CLK	Q	$\bar{Q}$	
1	↑	1	0	SET
0	↑	0	1	RESET

Shift registers can form useful counters by recirculating a pattern of 0's and 1's. Two important shift register counters are the *Johnson counter* and the *ring counter*.

The Johnson counter is useful when you need a sequence that **changes by only one bit at a time** but it has a limited number of states ( $2n$ , where  $n$  = number of stages).

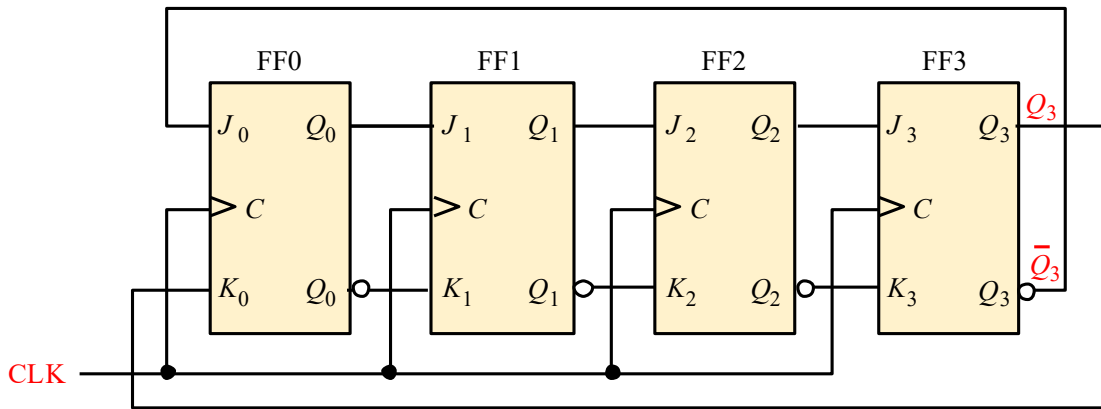


CLK	$Q_0$	$Q_1$	$Q_2$	$Q_3$
0	0	0	0	0
1	1	0	0	0
2	1	1	0	0
3	1	1	1	0
4	1	1	1	1
5	0	1	1	1
6	0	0	1	1
7	0	0	0	1

The Johnson counter can be made with a series of D flip-flops

# Shift Registers

## Johnson Counter



Inputs			Outputs		Comments
J	K	CLK	Q	$\bar{Q}$	
0	0	↑	$Q_0$	$\bar{Q}_0$	No change
0	1	↑	0	1	RESET
1	0	↑	1	0	SET
1	1	↑	$\bar{Q}_0$	$Q_0$	Toggle

CLK	$Q_0$	$Q_1$	$Q_2$	$Q_3$
0	0	0	0	0
1	1	0	0	0
2	1	1	0	0
3	1	1	1	0
4	1	1	1	1
5	0	1	1	1
6	0	0	1	1
7	0	0	0	1

... or with a series of J-K flip flops. Here  $Q_3$  and  $\bar{Q}_3$  are fed back to the  $J$  and  $K$  inputs with a “twist”.

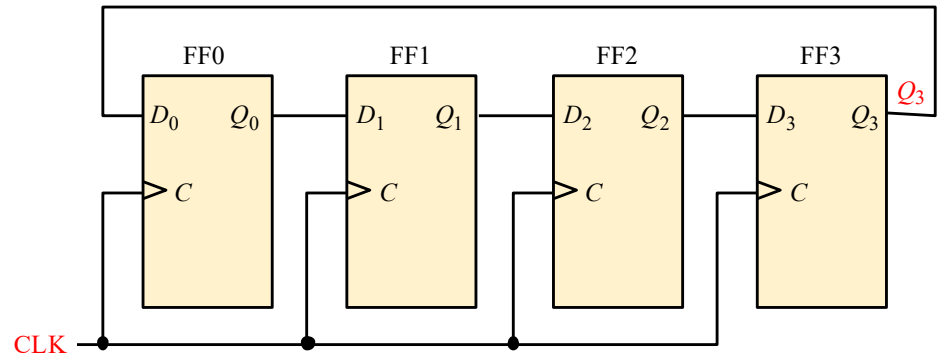


# Shift Registers

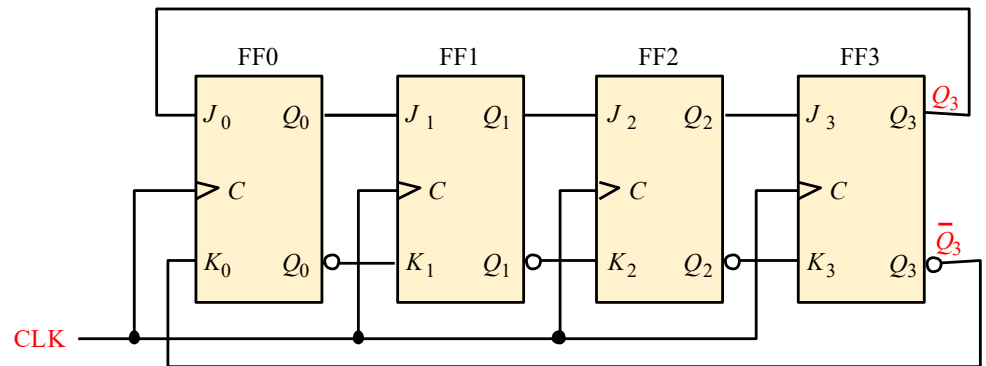
## Ring Counter

The ring counter can also be implemented with either D flip-flops or J-K flip-flops.

Here is a 4-bit ring counter constructed from a series of D flip-flops. Notice the feedback.



Like the Johnson counter, it can also be implemented with J-K flip flops.



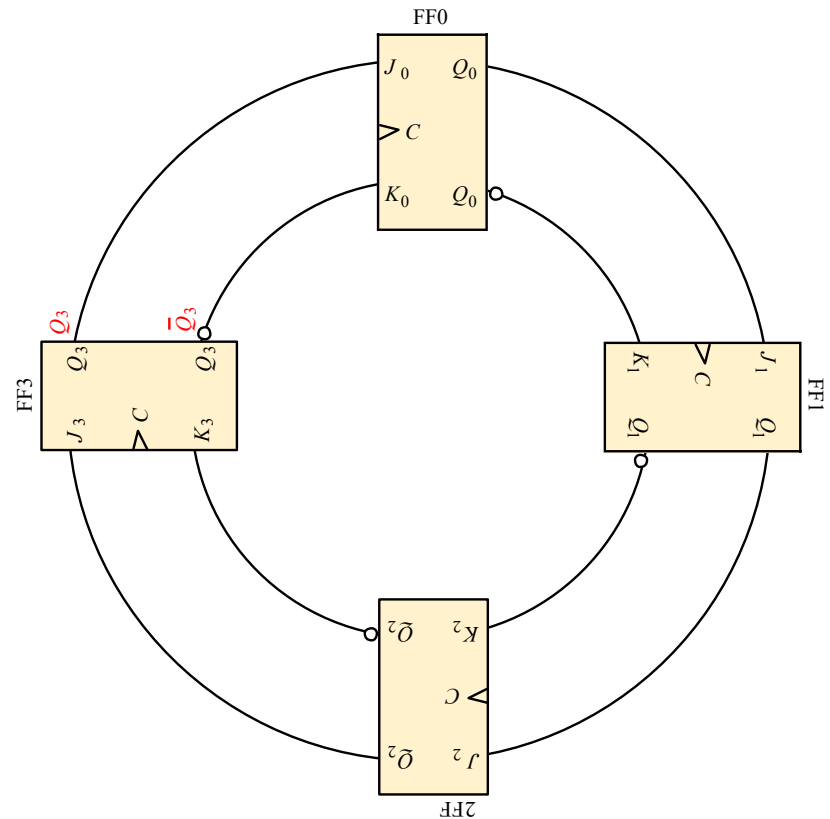
# Shift Registers

## Ring Counter

Redrawing the Ring counter (without the clock shown) shows why it is a “ring”.

The disadvantage to this counter is that it must be preloaded with the desired pattern (usually a single 0 or 1) and **it has states number** ( $n$ , where  $n$  = number of flip-flops).

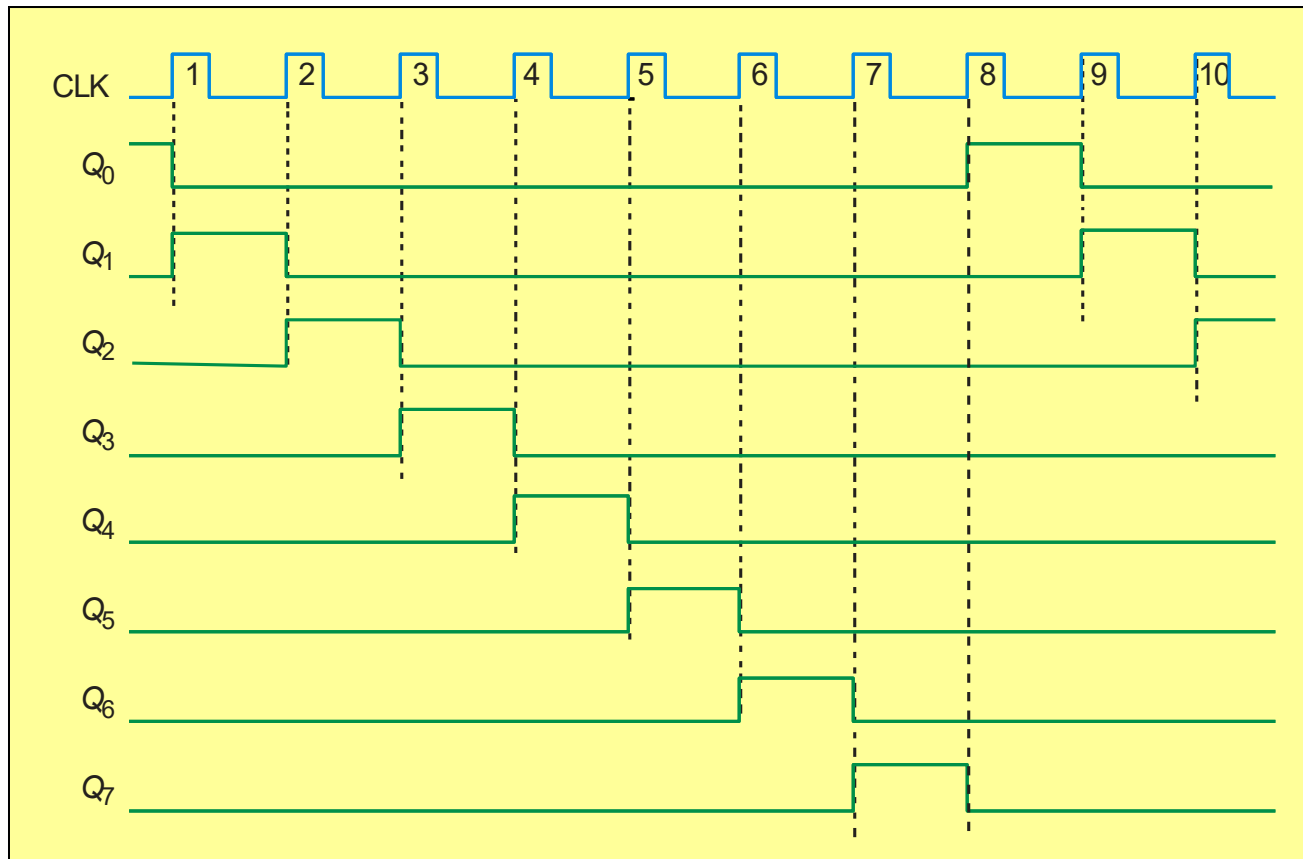
On the other hand, it has the advantage of being self-decoding with a unique output for each state.



# Shift Registers

## Ring Counter

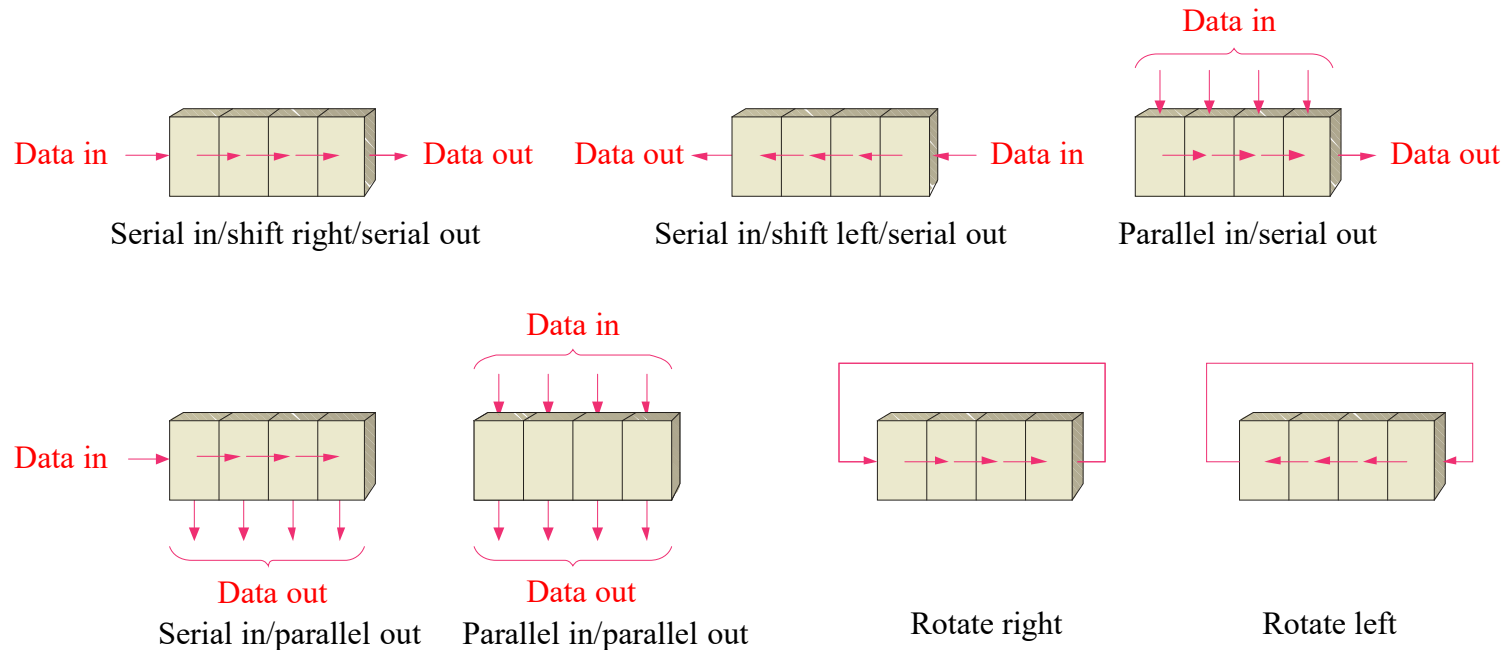
A common pattern for a ring counter is to load it with a single 1 or a single 0. The waveforms shown here are for an 8-bit ring counter with a single 1.



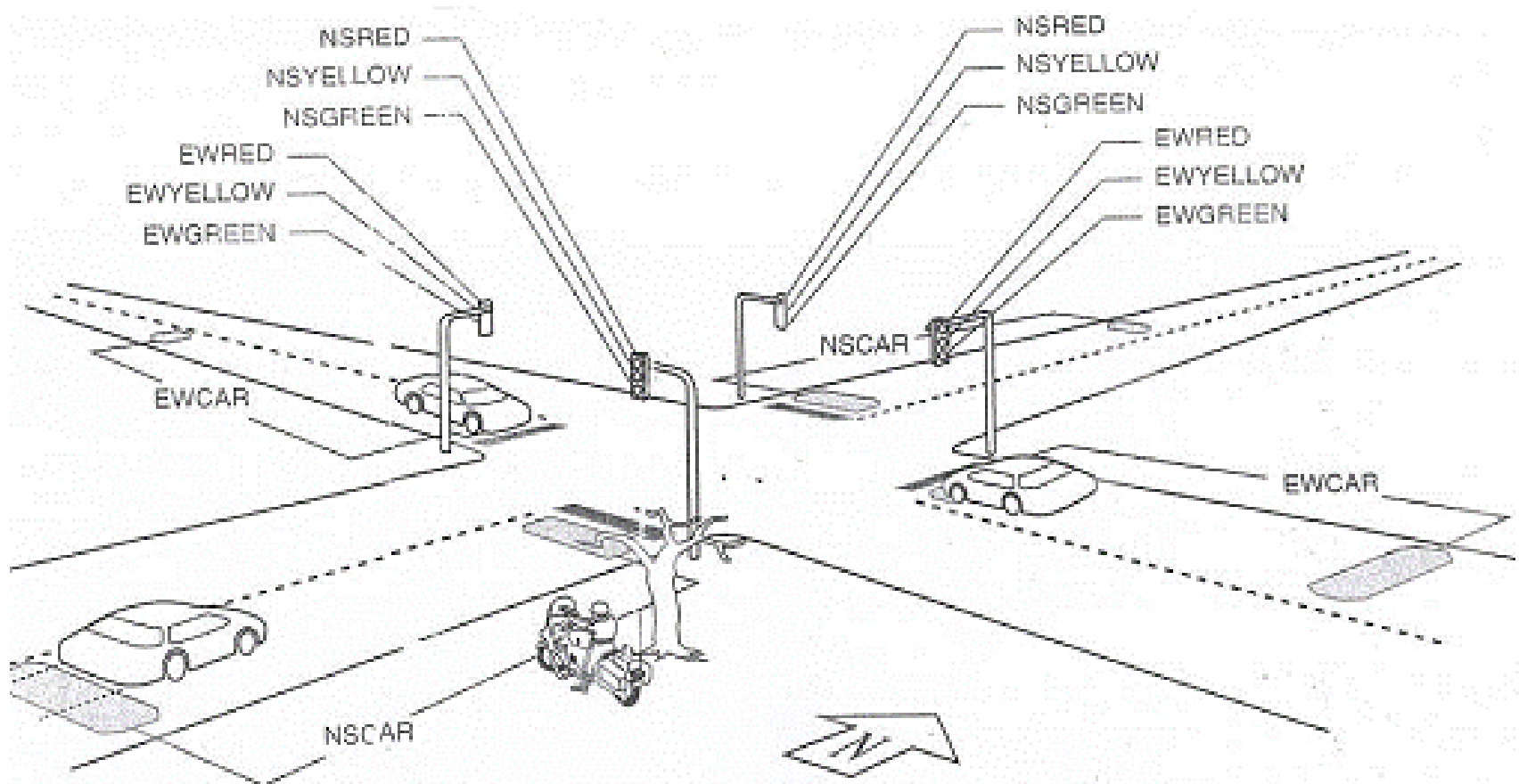
# Shift Registers

## Basic Shift Register Operations

A shift register is an arrangement of flip-flops with important applications in storage and movement of data. Some basic data movements are illustrated here.



# Application: Traffic Light Controller



# Application: Traffic Light Controller

